

(Time to complete = 1 hour)

4) What means "rate of change of angular momentum"?

Consider a moving point C (moving relative to a Newtonian frame F that has an origin O). For which of these definitions of \vec{H}/C is the following equation of motion true (that is, consistent with $\vec{F} = m\vec{a}$)?

$$\vec{M}_C = \dot{\vec{H}}/C$$

a) $\vec{H}/C = \vec{r}_{P/C'} \times \vec{v}_{P/O}$

where C' is a point fixed in F that instantaneously coincides with C

$$\Rightarrow \dot{\vec{H}}/C = (\dot{\vec{r}}_{P/C'} \times \vec{v}_{P/O}) + (\vec{r}_{P/C'} \times \dot{\vec{v}}_{P/O})$$

$$\dot{\vec{H}}/C = (\vec{v}_{P/C'} \times \vec{v}_{P/O}) + (\vec{r}_{P/C'} \times \vec{a}_{P/O})$$

Since C' is fixed in F , its velocity is zero.

The origin of F is also not moving (is fixed).

Since C' and O are both fixed, the velocity of particle P with respect to C' and O will be the same

$$\Rightarrow \vec{v}_{P/C'} = \vec{v}_{P/O} \quad \checkmark$$

4) a) (continued)

$$\Rightarrow \dot{\vec{H}}_{/c} = (\cancel{\vec{v}_{p/o}} \times \vec{v}_{p/o}) + (\vec{r}_{p/c'} \times \vec{a}_{p/o})$$

$$\dot{\vec{H}}_{/c} = \vec{r}_{p/c'} \times \vec{a}_{p/o}$$

We also have the condition that c' instantaneously coincides with c


$$\Rightarrow \vec{r}_{p/c'} = \vec{r}_{p/c}$$

We then have

$$\dot{\vec{H}}_{/c} = \vec{r}_{p/c} \times \vec{a}_{p/o}$$

Finally, since the Newtonian frame F has an origin O , we know that $\vec{a}_{p/o} = \vec{a}_{p/F}$

$$\Rightarrow \boxed{\dot{\vec{H}}_{/c} = \vec{r}_{p/c} \times \vec{a}_{p/F}}$$


 \Rightarrow It has been shown that this definition works in general.

4) b)

$$\vec{H}/c = \vec{r}_{p/c} \times \vec{v}_{p/o}$$

Since C is a moving point, we can write

$$\vec{v}_{p/o} = \vec{v}_{p/c} + \vec{v}_{c/o}$$

$$\Rightarrow \vec{H}/c = \vec{r}_{p/c} \times (\vec{v}_{p/c} + \vec{v}_{c/o})$$

$$\vec{H}/c = (\vec{r}_{p/c} \times \vec{v}_{p/c}) + (\vec{r}_{p/c} \times \vec{v}_{c/o})$$

Taking the time derivative, we get

$$\begin{aligned} \dot{\vec{H}}/c &= (\dot{\vec{r}}_{p/c} \times \vec{v}_{p/c}) + (\vec{r}_{p/c} \times \dot{\vec{v}}_{p/c}) \\ &\quad + (\dot{\vec{r}}_{p/c} \times \vec{v}_{c/o}) + (\vec{r}_{p/c} \times \dot{\vec{v}}_{c/o}) \end{aligned}$$

$$\begin{aligned} \dot{\vec{H}}/c &= (\cancel{\vec{v}_{p/c}} \times \vec{v}_{p/c}) + (\vec{r}_{p/c} \times \vec{a}_{p/c}) \\ &\quad + (\vec{v}_{p/c} \times \vec{v}_{c/o}) + (\vec{r}_{p/c} \times \vec{a}_{c/o}) \end{aligned}$$

$$\Rightarrow \dot{\vec{H}}/c = (\vec{r}_{p/c} \times \vec{a}_{p/c}) + (\vec{v}_{p/c} \times \vec{v}_{c/o}) + (\vec{r}_{p/c} \times \vec{a}_{c/o})$$

We also know that

$$\vec{a}_{p/o} = \vec{a}_{p/c} + \vec{a}_{c/o}$$

4) b) (continued)

Thus, we can write

$$(\vec{r}_{P/C} \times \vec{a}_{P/C}) + (\vec{r}_{P/C} \times \vec{a}_{C/O})$$

$$= \left[\vec{r}_{P/C} \times (\vec{a}_{P/C} + \vec{a}_{C/O}) \right]$$

$$= \vec{r}_{P/C} \times \vec{a}_{P/O}$$

Plugging this into the original expression yields

$$\dot{\vec{H}}_{I/C} = (\vec{r}_{P/C} \times \vec{a}_{P/O}) + (\vec{v}_{P/C} \times \vec{v}_{C/O})$$

Again, since O is the origin of the Newtonian frame F , $\vec{a}_{P/O} = \vec{a}_{P/F}$

$$\Rightarrow \boxed{\dot{\vec{H}}_{I/C} = (\vec{r}_{P/C} \times \vec{a}_{P/F}) + (\vec{v}_{P/C} \times \vec{v}_{C/O})}$$

In order for our expression for $\dot{\vec{H}}_{I/C}$ to equal what we need, $(\vec{v}_{P/C} \times \vec{v}_{C/O})$ must equal 0 .

4) b) (continued)

$(\vec{v}_{P/C} \times \vec{v}_{C/O}) = 0$ if the following scenarios are true:

$$\vec{v}_{P/C} = 0$$

\Rightarrow The particle P and the point C are moving at the same velocity with respect to the origin of the Newtonian frame \mathcal{F}

$$\vec{v}_{C/O} = 0$$

\Rightarrow The point C is stationary with respect to the origin of the Newtonian frame \mathcal{F} (can only happen instantaneously)

$$\vec{v}_{P/C} \times \vec{v}_{C/O} = 0$$

\Rightarrow The particle P is moving in the same direction with respect to point C as the point C is moving away from the origin of the Newtonian frame \mathcal{F} or in the opposite direction.

\Rightarrow Motion of particle P with respect to the point C is in-line with point C's motion with respect to the origin of the Newtonian frame \mathcal{F} .

4) b) (continued)

⇒ Definition works for some special cases concerning the motions of P and C that I previously specified.

4) c)

$$\vec{H}_{1C} = \vec{r}_{P1C} \times \vec{v}_{P1C}$$

Again, we have $\vec{v}_{P10} = \vec{v}_{P1C} + \vec{v}_{C10}$

$$\Rightarrow \vec{v}_{P1C} = \vec{v}_{P10} - \vec{v}_{C10}$$

Plugging this in, we get

$$\vec{H}_{1C} = \vec{r}_{P1C} \times (\vec{v}_{P10} - \vec{v}_{C10})$$

$$\vec{H}_{1C} = (\vec{r}_{P1C} \times \vec{v}_{P10}) - (\vec{r}_{P1C} \times \vec{v}_{C10})$$

\Rightarrow Differentiating with respect to time gives

$$\begin{aligned} \dot{\vec{H}}_{1C} &= (\dot{\vec{r}}_{P1C} \times \vec{v}_{P10}) + (\vec{r}_{P1C} \times \dot{\vec{v}}_{P10}) \\ &\quad - \left[(\dot{\vec{r}}_{P1C} \times \vec{v}_{C10}) + (\vec{r}_{P1C} \times \dot{\vec{v}}_{C10}) \right] \end{aligned}$$

$$\begin{aligned} \dot{\vec{H}}_{1C} &= (\vec{v}_{P1C} \times \vec{v}_{P10}) + (\vec{r}_{P1C} \times \vec{a}_{P10}) \\ &\quad - \left[(\vec{v}_{P1C} \times \vec{v}_{C10}) + (\vec{r}_{P1C} \times \vec{a}_{C10}) \right] \end{aligned}$$

4) c) (continued)

We know that $\vec{v}_{p/o} = \vec{v}_{p/c} + \vec{v}_{c/o}$

$$\Rightarrow \vec{v}_{p/c} = \vec{v}_{p/o} - \vec{v}_{c/o}$$

We can rewrite the original expression as

$$\begin{aligned} \dot{\vec{H}}/c &= (\vec{v}_{p/c} \times \vec{v}_{p/o}) - (\vec{v}_{p/c} \times \vec{v}_{c/o}) \\ &\quad + (\vec{r}_{p/c} \times \vec{a}_{p/o}) - (\vec{r}_{p/c} \times \vec{a}_{c/o}) \end{aligned}$$

$$\begin{aligned} \dot{\vec{H}}/c &= \vec{v}_{p/c} \times (\vec{v}_{p/o} - \vec{v}_{c/o}) + (\vec{r}_{p/c} \times \vec{a}_{p/o}) \\ &\quad - (\vec{r}_{p/c} \times \vec{a}_{c/o}) \end{aligned}$$

$$\dot{\vec{H}}/c = \cancel{\vec{v}_{p/c} \times (\vec{v}_{p/c})}^0 + (\vec{r}_{p/c} \times \vec{a}_{p/o}) - (\vec{r}_{p/c} \times \vec{a}_{c/o})$$

$$\dot{\vec{H}}/c = (\vec{r}_{p/c} \times \vec{a}_{p/o}) - (\vec{r}_{p/c} \times \vec{a}_{c/o})$$

Again, since o is the origin of the Newtonian frame \mathcal{F} , we can write $\vec{a}_{p/o} = \vec{a}_{p/\mathcal{F}}$

4) c) (continued)

$$\Rightarrow \dot{\vec{h}}_{|c} = (\vec{r}_{p|c} \times \vec{a}_{p|F}) - (\vec{r}_{p|c} \times \vec{a}_{c|o})$$

In order for this expression to equal what we want, we need $(\vec{r}_{p|c} \times \vec{a}_{c|o}) = 0$

This is true if

$$\vec{r}_{p|c} = 0$$

\Rightarrow Particle P and the point C are always at the same point in space with respect to the origin of the Newtonian frame F

$$\vec{a}_{c|o} = 0$$

\Rightarrow The point C is not accelerating with respect to the origin O

$$(\vec{r}_{p|c} \times \vec{a}_{c|o}) = 0$$

\Rightarrow The acceleration of point C with respect to the origin O is in-line with the position vector from point C to particle P.

4) c) (continued)

=>

Definition works for some special cases concerning the motions of P and C that \neq previously specified.