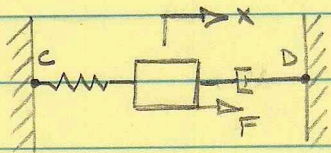
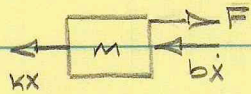


21a.



- (15 min) i. For the case that C and D are fixed (as above) and a force $F = F_0 \sin \omega t$ acts on mass, determine A, B.



Linear Momentum Balance

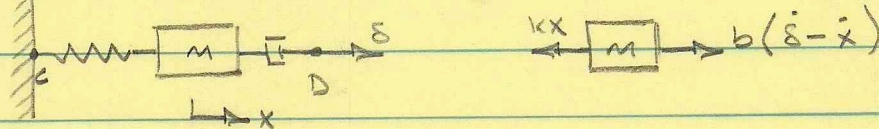
$$\sum F = m\ddot{x}$$

$$-kx - b\dot{x} + F = m\ddot{x}$$

$$m\ddot{x} + b\dot{x} + kx = F = F_0 \sin \omega t \rightarrow \boxed{A=0, B=F_0}$$

- (15 min) ii. For case where C is fixed and D oscillates with magnitude

$$\delta = \delta_0 \sin \omega t$$



Linear Momentum Balance

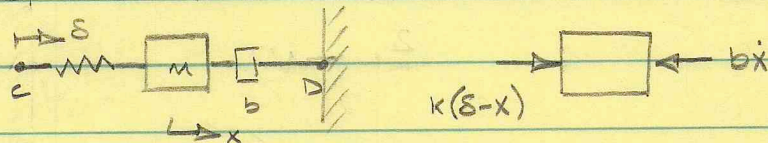
$$\sum F = m\ddot{x}$$

$$-kx + b(\dot{\delta} - \dot{x}) = m\ddot{x} \quad \text{where } \frac{d}{dt}(\delta) = \omega_0 \delta_0 \cos \omega_0 t$$

$$m\ddot{x} - b(\omega_0 \delta_0 \cos \omega_0 t - \dot{x}) + kx = 0$$

$$m\ddot{x} + b\dot{x} + kx = b\omega_0 \delta_0 \cos \omega_0 t \rightarrow \boxed{A = b\omega_0 \delta_0, B = 0}$$

- (15 min) iii. Case, where D is fixed and C oscillates with $\delta = \delta_0 \sin \omega_0 t$



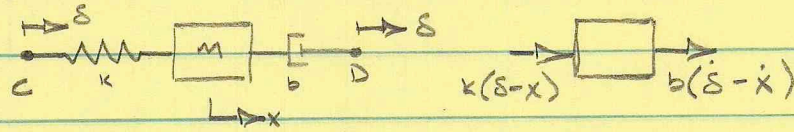
$$\sum F = m\ddot{x}$$

$$k(\delta - x) - b\dot{x} = m\ddot{x} \quad \text{where } \delta = \delta_0 \sin \omega_0 t$$

$$k(\delta_0 \sin \omega_0 t - x) - b\dot{x} = m\ddot{x}$$

$$m\ddot{x} + b\dot{x} + kx = k\delta_0 \sin \omega_0 t \rightarrow \boxed{A=0, B=k\delta_0}$$

(15 min) iv. Case when C and D oscillate together with $\delta = \delta_0 \sin \omega_0 t$



$$\Sigma F = m\ddot{x}$$

$$k(\delta - x) + b(\dot{\delta} - \dot{x}) = m\ddot{x} \quad \text{where } \delta = \delta_0 \sin \omega_0 t, \quad \frac{d}{dt}(\delta) = \delta_0 \omega_0 \cos \omega_0 t$$

$$k(\delta_0 \sin \omega_0 t - x) + b(\delta_0 \omega_0 \cos \omega_0 t - \dot{x}) = m\ddot{x}$$

$$m\ddot{x} + b\dot{x} + kx = b\delta_0 \omega_0 \cos \omega_0 t + k\delta_0 \sin \omega_0 t \rightarrow \boxed{A = b\delta_0 \omega_0, B = k\delta_0}$$

b. Trivial coding, did not attempt.

