

① The function `iknowthis(t,z)` generates a first-order system of linear differential equations

$$\begin{aligned}\dot{x} &= y \\ \dot{y} &= -x\end{aligned}$$

This is equivalent to the second order differential equation

$$\ddot{x} + x = 0$$

(for an easy to see this, take the time derivative of $\dot{x} = y$ and use it with $y = -x$)

The characteristic equation of this second order linear differential equation is

$$r^2 + 1 = 0 \Leftrightarrow r^2 = -1 \Leftrightarrow r = \pm i$$

So the general solution is

$$x(t) = A \cos(t) + B \sin(t)$$

The initial conditions are

$$x(0) = 1$$

$$y(0) = \dot{x}(0) = 0$$

So we obtain $A = x(0) = 1$

and since $\dot{x}(t) = -A \sin(t) + B \cos(t)$,

$$B = \dot{x}(0) = 0$$

Thus

$$x(t) = \cos(t)$$

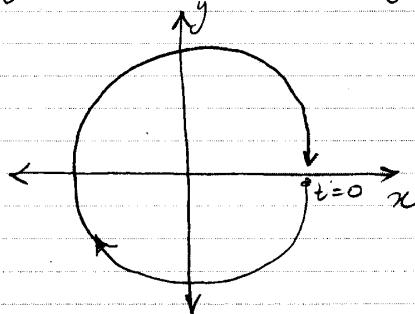
$$\text{and } y(t) = \dot{x}(t) = -\sin(t).$$

The plot of $x(t)$ vs $y(t)$ will be a parametric curve (time t is the parameter) with

$$x(t) = \cos(t) \quad \text{for } t = 0 \text{ to } 2\pi$$

$$y(t) = -\sin(t)$$

This will create a circle of radius 1 starting at $(1, 0)$ and moving clockwise...



The following are the two files you were asked to run

```
% These 4 lines are in a script file
[t,z]=ODE23('iknowthis', [0 2*pi], [1 0]);
plot(z(:,1), z(:,2))
axis('square')
```

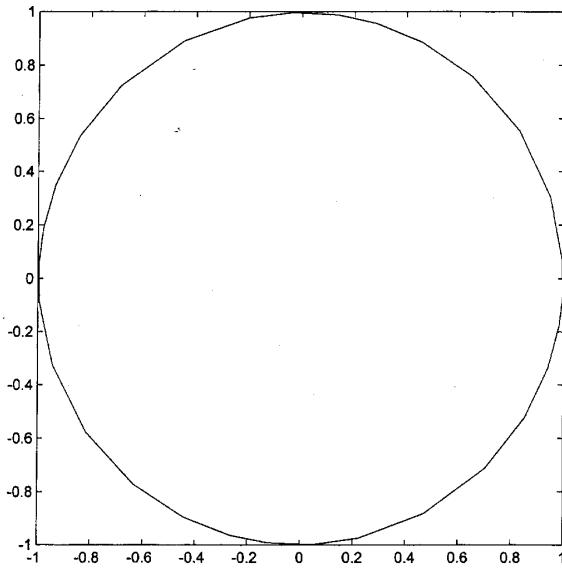
```
% These seven lines are in the file iknowthis.m
z1 = z(1);
z2 = z(2);
```

```
z1dot= z2;
```

```
z2dot= -z1;
```

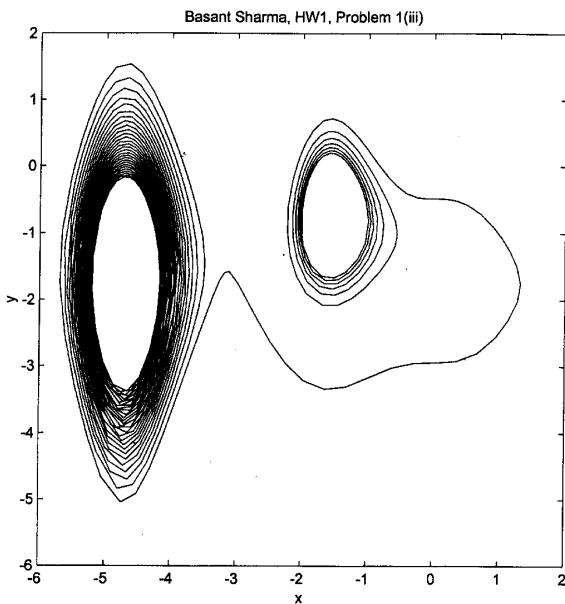
```
zdot=[z1dot, z2dot]';
```

This results in the figure shown below...



```
% These 4 lines are in a script file
options=odeset('RelTol',1e-8,'AbsTol',1e-8);
[t,z]=ODE23('iknowthis', [-10 50], [-2 -1]);
plot(z(:,1), z(:,2))
axis('square')
xlabel('x');
ylabel('y');
title('Basant Sharma, HW1, Problem 1(iii)');
% These seven lines are in the file iknowthis.m
z1 = z(1);
z2 = z(2);

z1dot= 1+z2+sin(z1)+cos(z2);
z2dot= -2*z1*sin(2*z1);
zdot=[z1dot, z2dot];
%
```



Given

$\vec{F}_1 = 5N \text{ along } OA$

$\vec{F}_2 = 7N \text{ along } OB$

g) $\vec{n}_{OB} = \text{unit vector along } OB$

$$= \frac{4\hat{i} + 3\hat{j} + 5\hat{k}}{\sqrt{4^2 + 3^2 + 5^2}} \text{ m}$$

$$= \frac{1}{\sqrt{34}} (4\hat{i} + 3\hat{j} + 5\hat{k})$$

b) $\vec{n}_{OA} = \frac{\vec{OA}}{|OA|} = \frac{3\hat{j} + 5\hat{k}}{\sqrt{3^2 + 5^2}} \text{ m} = \frac{1}{\sqrt{34}} (3\hat{j} + 5\hat{k})$

g) $\vec{F}_1 = |\vec{F}_1| \vec{n}_{OA} = \frac{5}{\sqrt{34}} (3\hat{j} + 5\hat{k}) \text{ N} ;$

$\vec{F}_2 = |\vec{F}_2| \vec{n}_{OB} = \frac{7}{\sqrt{34}} (4\hat{i} + 3\hat{j} + 5\hat{k}) \text{ N} ;$

d) $\cos(\angle AOB) = \vec{n}_{OA} \cdot \vec{n}_{OB} = \frac{1}{10\sqrt{17}} (3 \times 3 + 5 \times 5)$

$$= \frac{1}{10\sqrt{17}} \times 34$$

$\therefore \angle AOB = \cos^{-1} \frac{34}{10\sqrt{17}} \approx 34.45^\circ$

e) Component of \vec{F}_1 in x -direction

$$\vec{F}_{1x} = \vec{F}_1 \cdot \hat{i} = \frac{5}{\sqrt{34}} (3\hat{j} + 5\hat{k}) \cdot \hat{i} \text{ N}$$

$$= 0 \text{ N}$$

f) Moment of \vec{F}_1 about point D

$$\vec{r}_{DO} \times \vec{F}_1 = DO \times \vec{F}_1 = -4\hat{i} m \times \frac{5}{\sqrt{34}} (3\hat{j} + 5\hat{k}) \text{ Nm}$$

$$= \frac{-20}{\sqrt{34}} (\hat{3j} - \hat{5k}) \text{ Nm}$$

$$= \frac{20}{\sqrt{34}} (\hat{5j} - \hat{3k}) \text{ Nm}$$

g) Moment of \vec{F}_2 about the axis DC = $\hat{j} \cdot (x_{DO} \times \vec{F}_2)$

$$= \hat{j} \cdot (-4\hat{i} m \times \frac{7}{\sqrt{34}} (4\hat{i} + 3\hat{j} + 5\hat{k}) \text{ N}) = \hat{j} \cdot \frac{28}{\sqrt{34}} (\hat{8k} + \hat{5i}) \text{ Nm}$$

$$= 14\sqrt{2} \text{ Nm}$$

h) $\hat{j} \cdot (x_{CO} \times \vec{F}_2) = \hat{j} \cdot [(-4\hat{i} - 3\hat{j}) m \times \frac{7}{\sqrt{34}} (4\hat{i} + 3\hat{j} + 5\hat{k}) \text{ N}]$

$$= \hat{j} \cdot \frac{7}{\sqrt{34}} (-12\hat{k} + 20\hat{j} + 12\hat{k} - 15\hat{i}) \text{ Nm}$$

$$= 14\sqrt{2} \text{ Nm} \text{ as before}$$

Also, $\hat{j} \cdot (x_{CB} \times \vec{F}_2) = \hat{j} \cdot [5\hat{k} m \times \frac{7}{\sqrt{34}} (4\hat{i} + 3\hat{j} + 5\hat{k}) \text{ N}]$

$$= \frac{7}{\sqrt{34}} \hat{j} \cdot (4\hat{j} - 3\hat{i}) \text{ Nm} = 14\sqrt{2} \text{ Nm}$$