

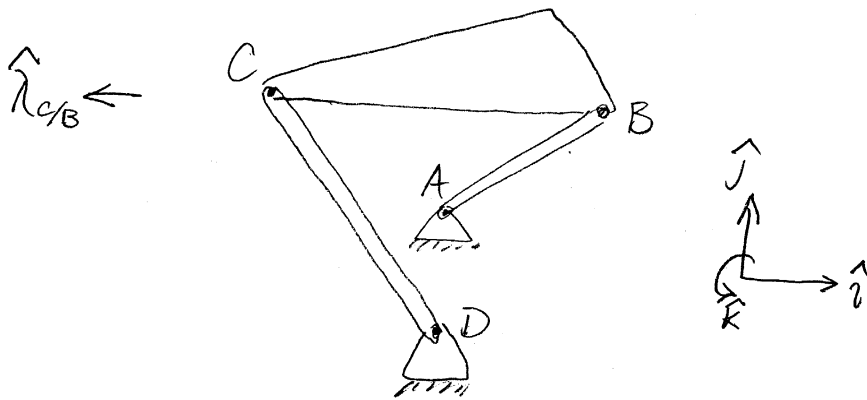
HW 18 (Assigned on Mar. 30, due on April 6.)

Solution by Dennis Young

6.1.23

$$\vec{r}_{C/B} = -0.4m\hat{i}, \quad \vec{r}_{A/B} = -0.2m\hat{i} - 0.1m\hat{j}$$

$$\vec{r}_{D/C} = 0.2m\hat{i} - 0.2m\hat{j}, \quad \vec{\omega}_{AB} = -2\hat{k} \text{ rad/s}$$

Find \vec{v}_C and $\vec{\omega}_{CD}$.Solution

$$\text{Let } \vec{\omega}_{CD} = \omega_{CD}\hat{k}$$

$$\text{take } \hat{\lambda}_{C/B} = \frac{\vec{r}_{C/B}}{\|\vec{r}_{C/B}\|} = \frac{-0.4m\hat{i}}{0.4m} = -\hat{i}$$

$$\text{Consider link } \overline{CD} : \vec{v}_C = \vec{v}_D + \vec{\omega}_{CD} \times \vec{r}_{C/D} = \vec{\omega}_{CD} \times (-\vec{r}_{D/C})$$

$$= \omega_{CD}\hat{k} \times (-0.2m\hat{i} + 0.2m\hat{j})$$

$$\Rightarrow \vec{v}_C = -0.2m \cdot \omega_{CD} \hat{j} + 0.2m \cdot \omega_{CD} (-\hat{i})$$

(a)

consider link \overline{AB} : $\vec{v}_B = \vec{v}_A + \vec{\omega}_{\overline{AB}} \times \vec{r}_{B/A}$

$$= \vec{\omega}_{\overline{AB}} \times (-\vec{r}_{A/B})$$

$$= -2 \text{ rad/s } \hat{k} \times (0.2 \text{ m } \hat{i} + 0.1 \text{ m } \hat{j})$$

$$\vec{v}_B = -2 \text{ rad/s} \cdot 0.2 \text{ m } \hat{j} + 2 \text{ rad/s} \cdot 0.1 \text{ m } \hat{i}$$

(b)

consider link \overline{CB} :

Both C and B are on the rigid link \overline{CB} .

thus $(\vec{v}_C - \vec{v}_B) \cdot \hat{\lambda}_{C/B} = 0$

(i.e., point C can NOT move (w.r.t. point B) along the direction of $\hat{\lambda}_{C/B}$, so the body has NO elongation or contraction along $\hat{\lambda}_{C/B}$)

by (a), (b) $\Rightarrow (\vec{v}_C - \vec{v}_B) \cdot \hat{\lambda}_{C/B} = (\vec{v}_C - \vec{v}_B) \cdot (-\hat{i}) = 0$

$\Rightarrow 0.2 \text{ m} \cdot \omega_{\overline{CB}} + 2 \text{ rad/s} \cdot 0.1 \text{ m} = 0$

$\Rightarrow \omega_{\overline{CB}} = -1 \text{ rad/s}$ $\omega_{\overline{CB}} = -1 \text{ rad/s } \hat{k}$

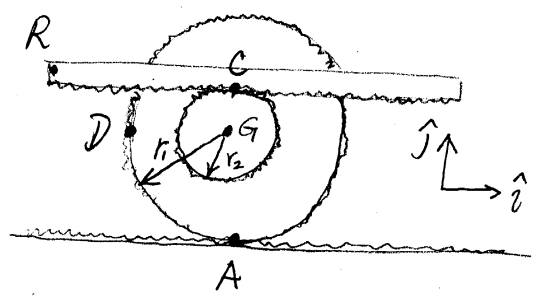
by (a) $\Rightarrow \vec{v}_C = 0.2 \text{ m/s } \hat{i} + 0.2 \text{ m/s } \hat{j}$

□

6.2.2

$\vec{v}_G = 1.2 \text{ m/s } \hat{i}$ $r_1 = 0.15 \text{ m}$, $r_2 = 0.1 \text{ m}$

Find $\vec{\omega}$ and \vec{v}_R, \vec{v}_D (using the instantaneous center of rotation)



Solution

Point A is the instantaneous center of rotation

let $\vec{\omega} = \omega \hat{k}$

$\vec{v}_G = \vec{\omega} \times \vec{r}_{G/A} = \omega \hat{k} \times r_1 \hat{j} = -\omega r_1 \hat{i}$ ①

$\vec{v}_R = \vec{v}_C = \vec{\omega} \times \vec{r}_{C/A} = \omega \hat{k} \times (r_1 + r_2) \hat{j} = -\omega (r_1 + r_2) \hat{i}$ ②

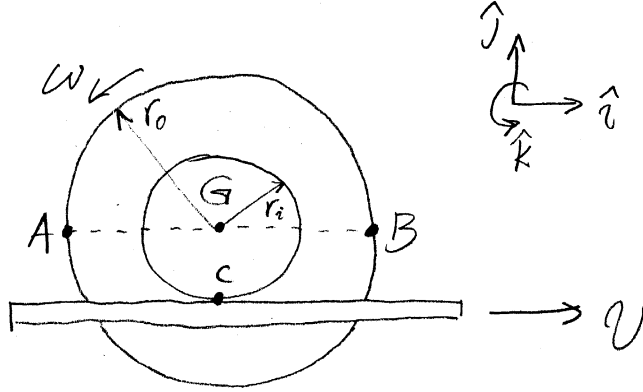
$\vec{v}_D = \vec{\omega} \times \vec{r}_{D/A} = \omega \hat{k} \times (-r_1 \hat{i} + r_1 \hat{j}) = -\omega r_1 \hat{j} - \omega r_1 \hat{i}$ ③

$\vec{v}_G = 1.2 \text{ m/s } \hat{i}$ & ① $\Rightarrow -\omega r_1 = 1.2 \text{ m/s}$
 $\Rightarrow \omega = \frac{1.2 \text{ m/s}}{-0.15 \text{ m}} = -8 \text{ rad/s}$

$\vec{\omega} = -8 \text{ rad/s } \hat{k}$

$\vec{v}_R = (-8 \text{ rad/s})(0.15 \text{ m} + 0.1 \text{ m}) \hat{i} \Rightarrow \vec{v}_R = 2 \text{ m/s } \hat{i}$

$\vec{v}_D = -(-8 \text{ rad/s}) 0.15 \text{ m/s } \hat{j} - (-8 \text{ rad/s}) 0.15 \text{ m/s } \hat{i} \Rightarrow \vec{v}_D = 1.2 \text{ m/s } \hat{i} + 1.2 \text{ m/s } \hat{j}$

6.2.9find \vec{v}_A , \vec{v}_B .Solution

$$\vec{v}_A = \vec{v}_C + \vec{\omega} \times \vec{r}_{A/C}$$

$$= v\hat{i} + \omega\hat{k} \times (-r_0\hat{i} + r_i\hat{j})$$

$$= v\hat{i} + (-\omega r_0\hat{j} - \omega r_i\hat{i})$$

$$\boxed{\vec{v}_A = (v - \omega r_i)\hat{i} - \omega r_0\hat{j}}$$

$$\vec{v}_B = \vec{v}_C + \vec{\omega} \times \vec{r}_{B/C}$$

$$= v\hat{i} + \omega\hat{k} \times (r_0\hat{i} + r_i\hat{j})$$

$$= v\hat{i} + \omega r_0\hat{j} - \omega r_i\hat{i}$$

$$\boxed{\vec{v}_B = (v - \omega r_i)\hat{i} + \omega r_0\hat{j}}$$

